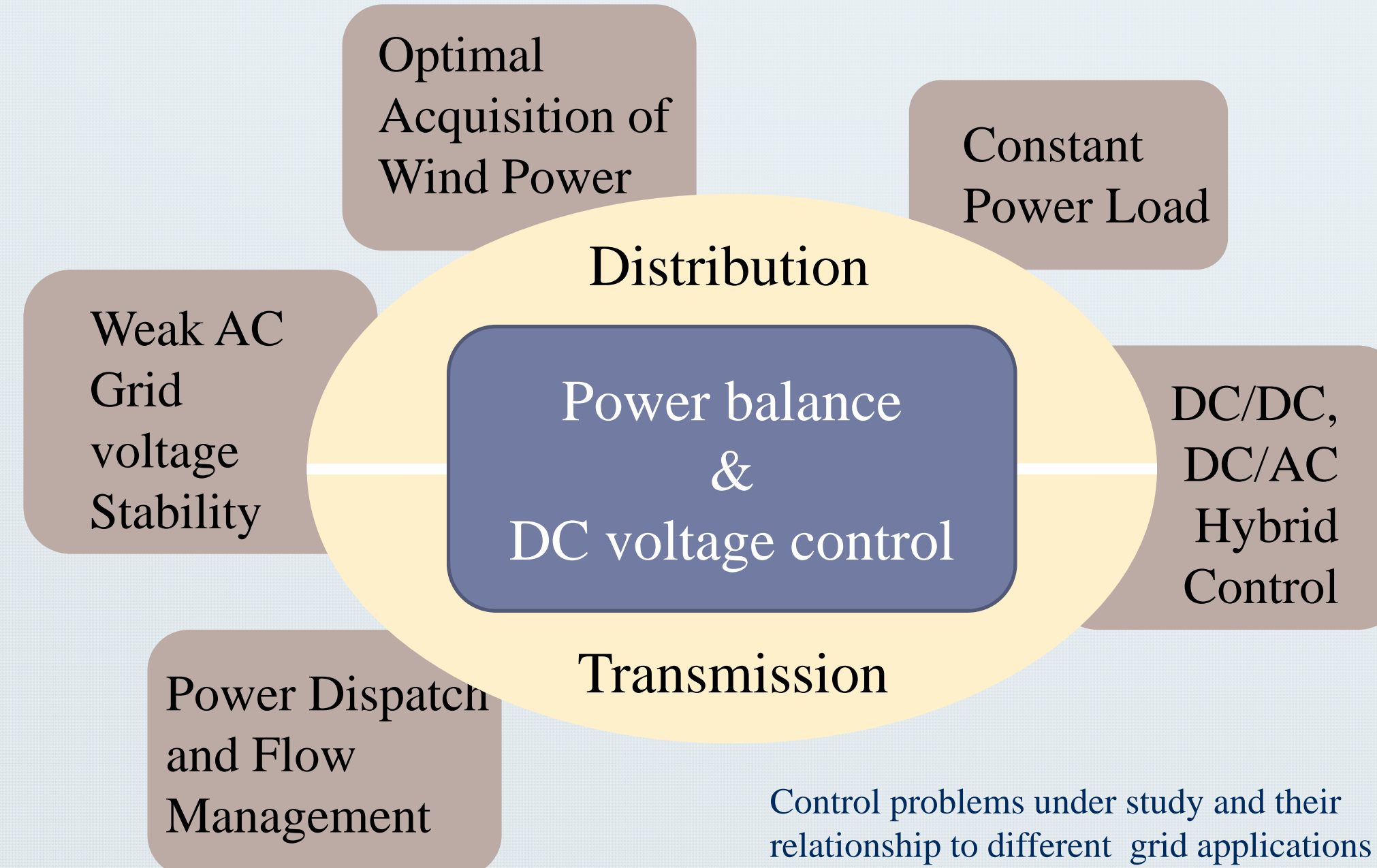


VSC-BASED MTDC SYSTEM

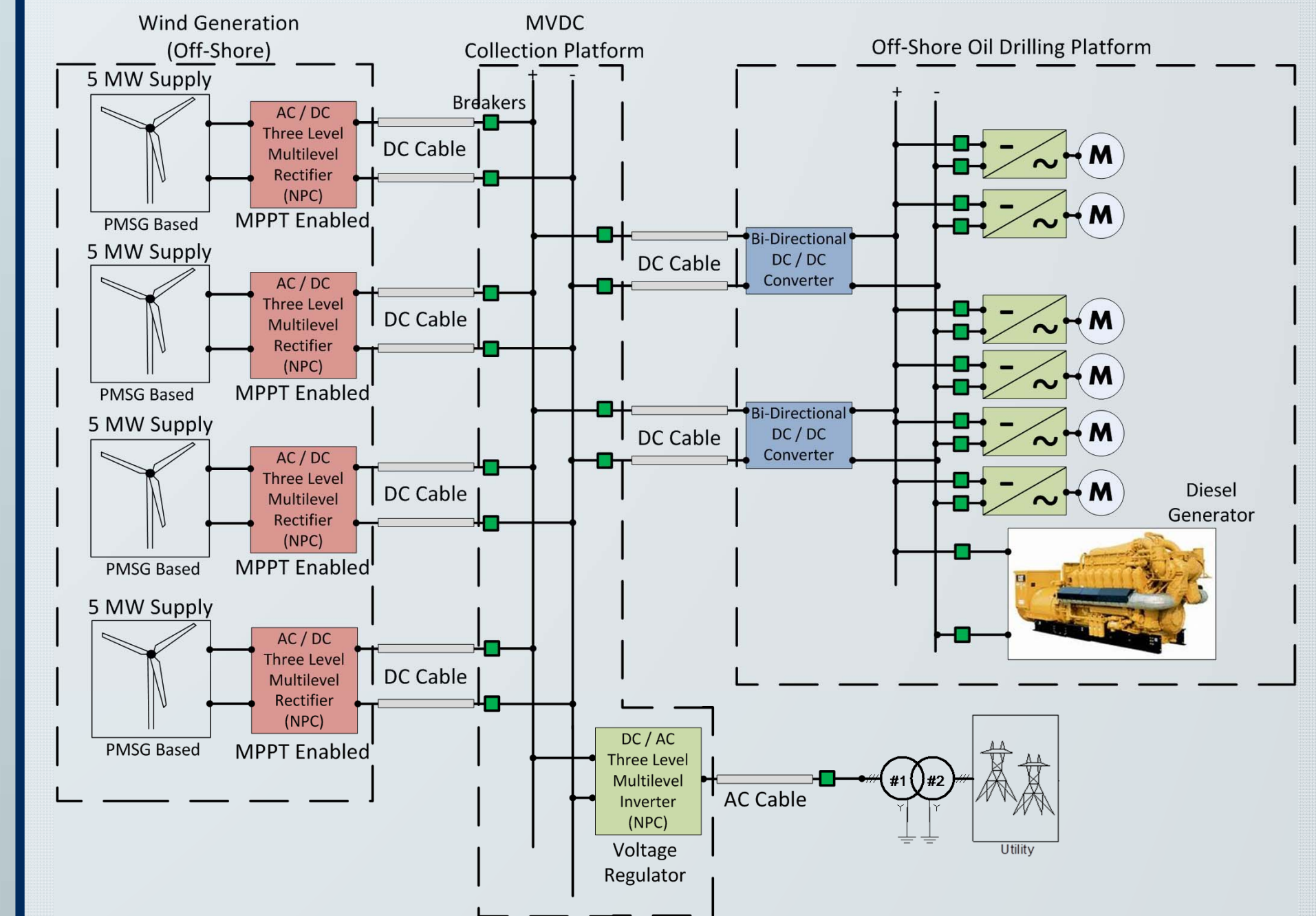
- ❖ Voltage Source Converter (VSC)
 - Independent control of real and reactive power exchange with AC systems
 - Appropriate technology for multi-terminal DC system
 - Higher converter loss due to switching
- ❖ Technical Limitations
 - DC breaker
 - Communication
 - Standards for operation and interface
- ❖ Possible Future Applications
 - Power distribution on vehicles
 - Backbone of microgrid
 - Offshore wind integration
 - SuperGrid: massive integration and transmission of renewable energy
 - AC islanding: splitting AC system into smaller segments

DC NETWORK CONTROL PROBLEMS UNDER INVESTIGATION



- ❖ Power balance is the core of stable DC grid operation
- ❖ Control Goals
 - DC voltage
 - AC stability or efficiency
 - Power dispatch
 - Converter's hard limit
- ❖ DC/DC converter node in a DC network
- ❖ Correlation and tradeoff between multiple control goals is a controllability problem
- ❖ Power Flow Management in Complex DC Network Topology
 - Converter can individually control power injection but not DC power flow
 - Distributed DC voltage control and reference setting
 - Cooperation between controllers is required

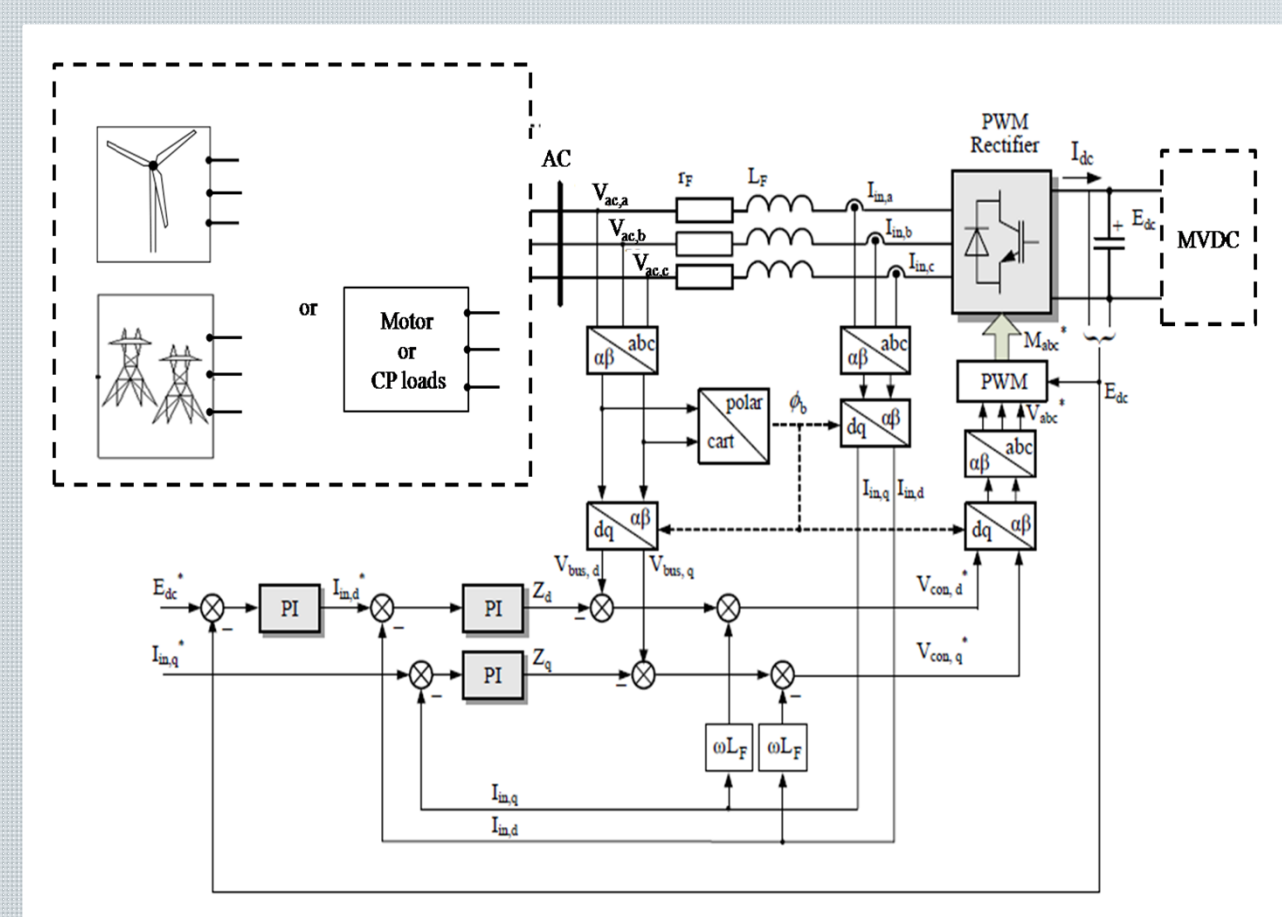
MTDC SYSTEMS UNDER STUDY



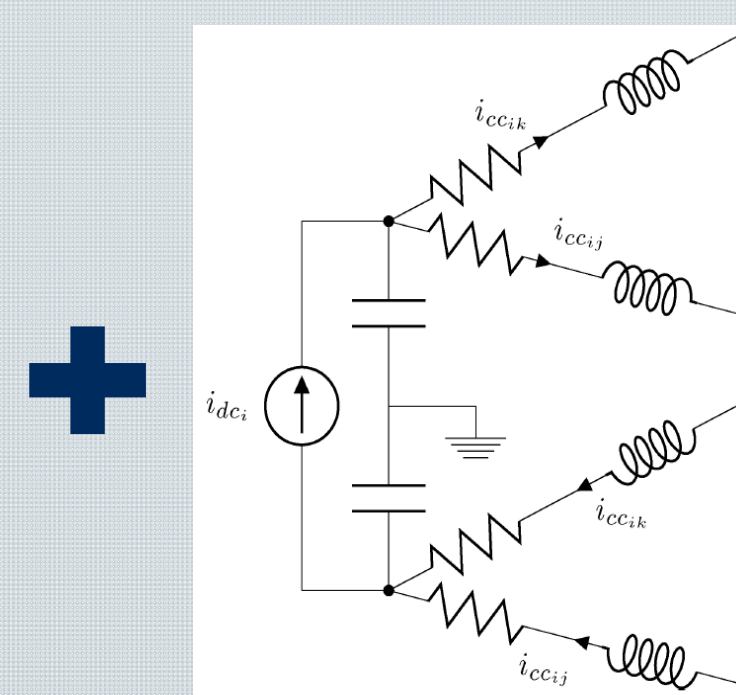
MVDC Microgrid for Offshore Wind Power and Oil Drilling Platform Integration
(by Brandon M. Grainger)

GRID LEVEL SYSTEM MODELING

- ❖ Coupling between subsystems will:
 - Cause instability in a stable subsystem
 - Help stabilize an unstable subsystem
 - Introduce conflicting control goals
- ❖ Grid Level Modeling
 - Study interaction among converters
 - Check stability in grid level
 - Coordinate local controllers



Model of Individual Converter as Basic Block



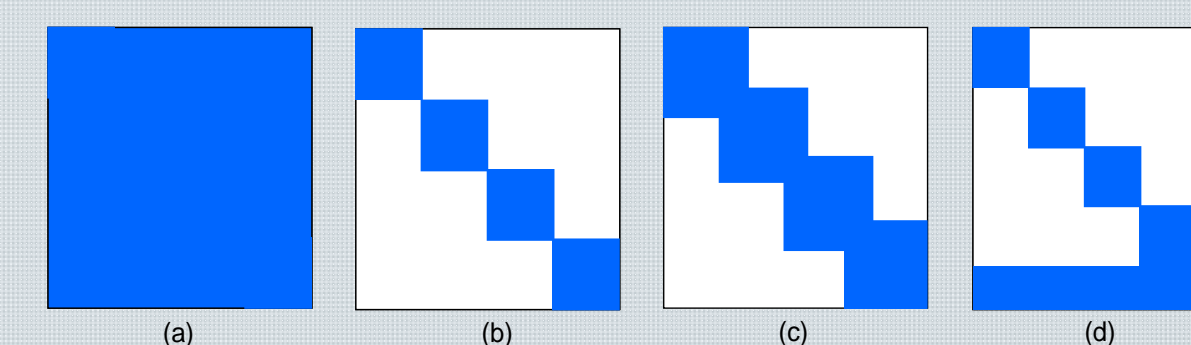
*Model of DC network as interconnection

$$\begin{bmatrix} \dot{x}_1 \\ \dot{x}_2 \\ \vdots \\ \dot{x}_{N-1} \\ \dot{x}_N \end{bmatrix} = \begin{bmatrix} A_{11} & A_{12} & \dots & A_{1,N-1} & A_{1N} \\ A_{21} & A_{22} & \dots & A_{2,N-1} & A_{2N} \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ A_{N-1,1} & A_{N-1,2} & \dots & A_{N-1,N-1} & A_{N-1,N} \\ A_{N1} & A_{N2} & \dots & A_{N,N-1} & A_{NN} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_{N-1} \\ x_N \end{bmatrix} + \begin{bmatrix} B_1 & 0 & \dots & 0 & 0 \\ 0 & B_2 & \dots & 0 & 0 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & \dots & B_{N-1} & 0 \\ 0 & 0 & \dots & 0 & B_N \end{bmatrix} \begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_{N-1} \\ u_N \end{bmatrix}$$

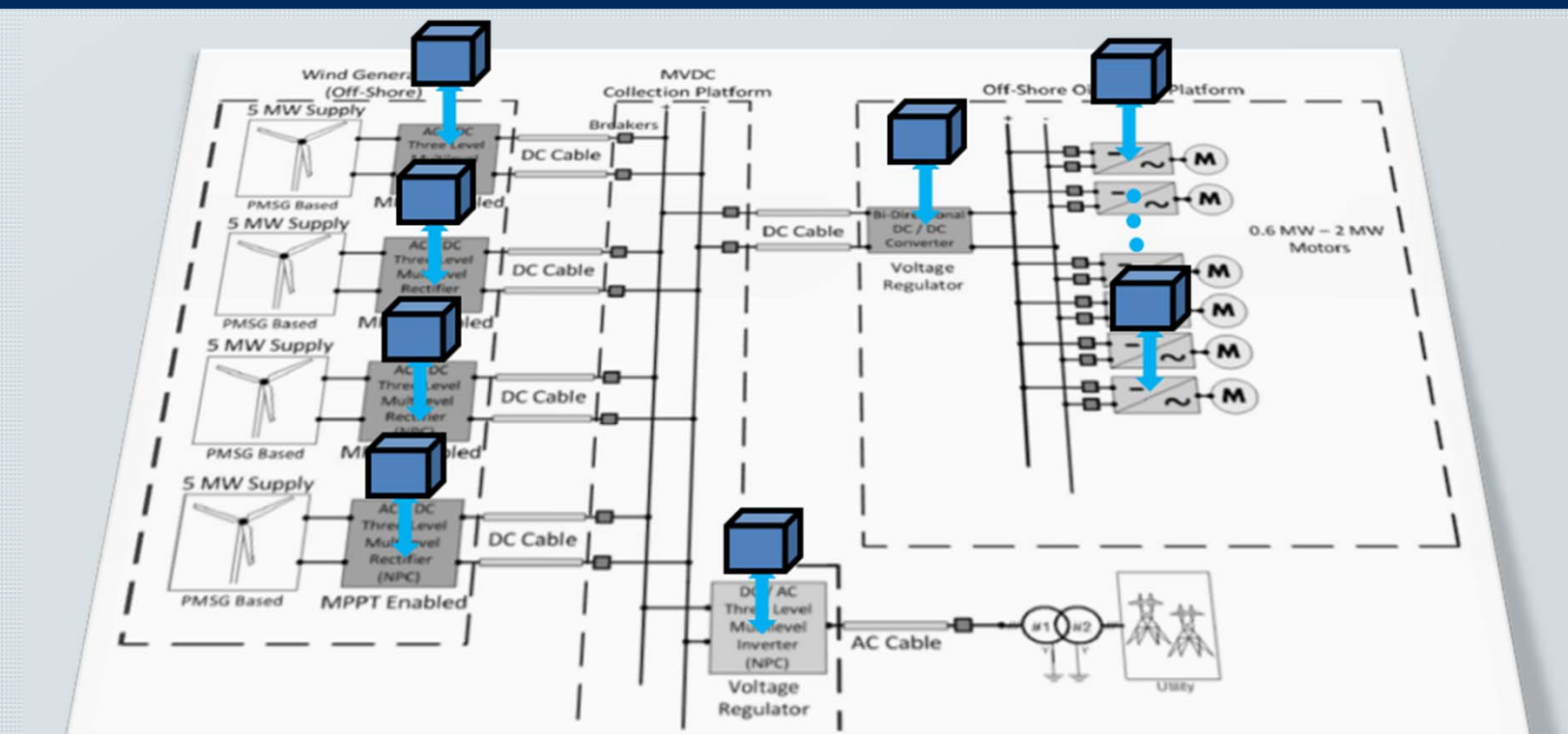
Grid Level Dynamic Model

CONTROL AND COMMUNICATION CO-DESIGN FOR DC POWER SYSTEMS

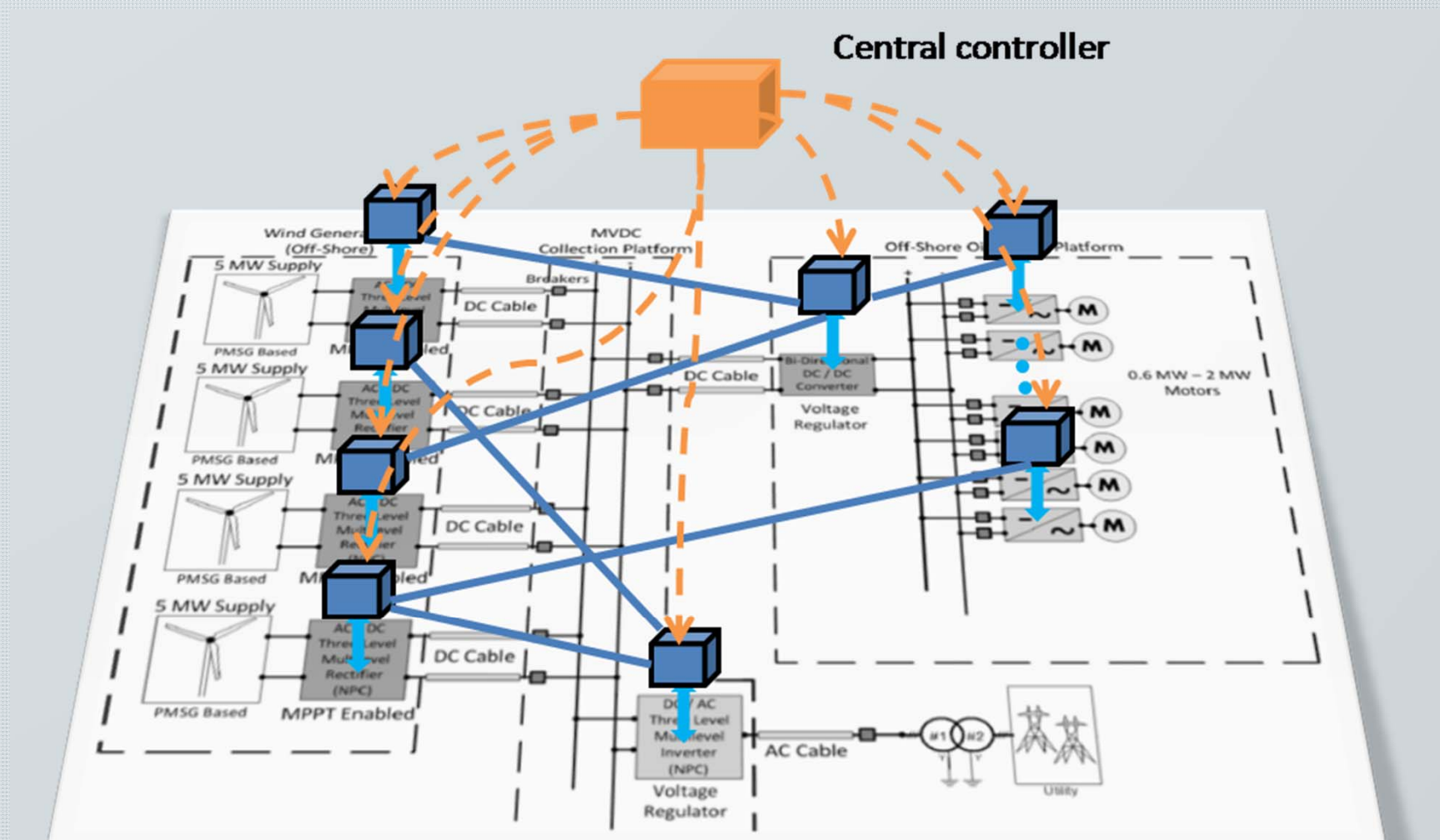
- ❖ Enable coordinated control between controllers to improve grid stability and efficiency
- ❖ Proposed Two Layer Hierarchical Controller
 - Lower layer: local controllers with possible communication with one another
 - Upper layer: single central controller adaptively optimizes topology of lower layer in real time
- ❖ Derived Innovative Control Algorithm to:
 - Solve the stabilization problem with arbitrary controller structure, with/without communication
 - Minimize the connection topology among distributed controllers, given the model of communication limits and complexity



Different controller structures can be indicated by different nonzero patterns of the control gain matrices



Decentralized, Non-Cooperative Control Architecture



Two-Layer Hierarchical Control Architecture